

# RTLA

Real-time Linux Analysis toolset



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# Real-time Linux

- Linux has been used as an RTOS - it is a fact!
- There are multiple reasons for people to use it
  - Software stack and availability
  - Man-power
- But also because Linux achieves the desired timing behavior
- Some key features to help on that are:
  - The fully preemptive mode
  - Real-time scheduling
    - SCHED\_DEADLINE

# Real-time Linux testing

- One of the problems, however, is the way that we show the timing properties of Linux
- Nowadays, Linux is tested using **blackbox tools** that mimic typical workload:
  - **Event** driven application: **cyclicttest**
  - **Polling** like application: **sysjitter/oslat**
- They report a "**latency**", and this is important for many use-cases. For example:
  - The kernel-rt has to deliver < 150 us cyclicttest latency under stress
  - cyclicttest latency of 10~20 us on isolated & tuned systems

# Real-time Linux testing

- **The blackbox approach works, but it has some drawbacks**
  - It gives no root cause analysis
- **The root cause analysis is generally done using tracing**
  - But tracing is not that accessible for non-experts
- **Real-time to the masses**
  - **All kernel developers will have to run RT analysis**
  - But not all are interested in learning all the details

# RTLA: A new approach



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# Real-time Linux Approach

- **RTLA follows a white-box approach**
- It integrates the workload and tracing
- In kernel:
  - Integrated tracer and workload
- In user-space
  - Easy to use interface
  - Data analysis

# RTLA: kernel tracers



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# Kernel tracers

- **RTLA uses two kernel tracers**
- **osnoise tracer**
  - Measures the Operating System noise/interference from high prio tasks
  - IOW: sysjitter/oslat on steroids
- **timerlat tracer**
  - Measures the activation delay of a timer triggered task
  - IOW: cyclicttest on steroids



osnoise tracer



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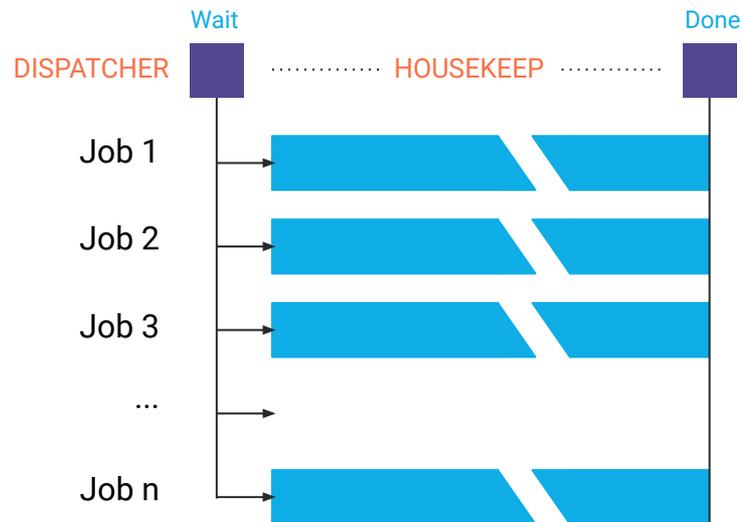
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# Operating system noise

- The Operating System Noise (**OS Noise**) is a well defined High Performance Computing (**HPC**) metric
- It is the amount of **interference** experienced by an application due to **operating system activities**
- It is generally a fine grained metric

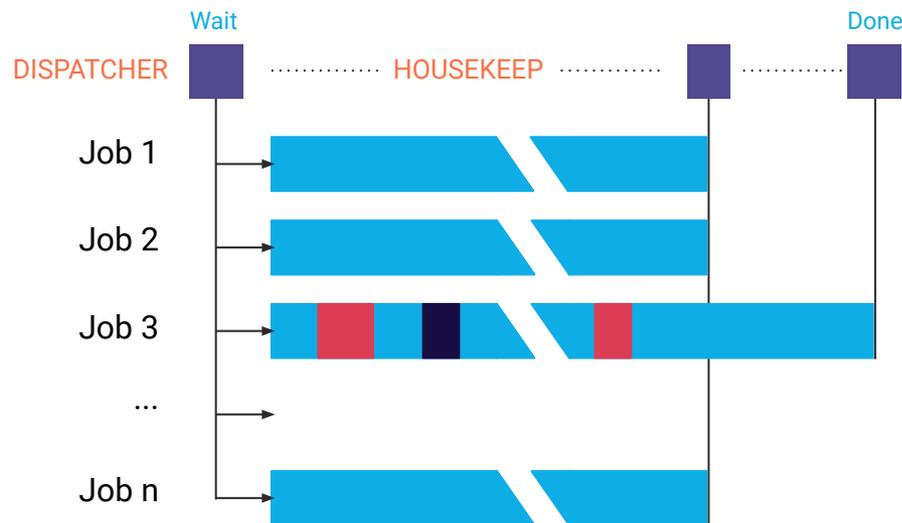
# Operating System noise

- Generally, HPC workloads are composed of **parallel jobs**
- The system is configured with **CPUs dedicated** to the jobs
- A dispatcher launches jobs to these CPUS and waits for completion



# Operating System noise

- The side effects of the OS Noise to the workload can influence the total response time of the system.
  - Both in parallel and pipeline workloads
- Some critical HPC RT workloads requires OS Noise to be less than 20 us.



# OS Noise tracer

- **osnoise** is a kernel tracer that also dispatches the workload
  - The workload runs in the kernel
- **It mimics HPC workload**
  - One thread per CPU
  - Detects noise by computing the delta between two consecutive reads of the time
- It has integrated tracing events to identify the source of the noise
  - In kernel lockless synchronization -> no false positives
- It detects high priority tasks that interfere the osnoise workload
  - osnoise can also detect hw/vm induced latency

# OS Noise tracer and safety critical systems

- It is common practice to **partition the system** in critical and non-critical domains
  - **Isolated/dedicated CPUs for critical workload**
    - Or even to a single workload or a middleware/framework
- The osnoise tracer is useful to:
  - **assess the partitioning/isolation**
  - identify how much interference the OS is adding to the critical load
    - Causing delay in the response time of critical workload

# Using the osnoise tracer

```
[root@f32 ~]# cd /sys/kernel/tracing/
[root@f32 tracing]# echo osnoise > current_tracer
[root@f32 tracing]# cat trace
# tracer: osnoise
#
#          _-----> irqs-off
#          / _-----> need-resched
#          | / _----> hardirq/softirq
#          || / _---> preempt-depth
#
#          || /
#          ||||
#          TASK-PID      CPU#  ||||   TIMESTAMP    RUNTIME
#          | |          |  ||||   |              |   IN US
#          <...>-859    [000]  ....   81.637220: 1000000
#          <...>-860    [001]  ....   81.638154: 1000000
#          <...>-861    [002]  ....   81.638193: 1000000
#          <...>-862    [003]  ....   81.638242: 1000000
#          <...>-863    [004]  ....   81.638260: 1000000
#          <...>-864    [005]  ....   81.638286: 1000000
#          <...>-865    [006]  ....   81.638302: 1000000
#          <...>-866    [007]  ....   81.638326: 1000000
```

NOISE IN US	% OF CPU AVAILABLE	NOISE IN US	Interference counters:					
			MAX SINGLE	HW	NMI	IRQ	SIRQ	THREAD
190	99.98100	9	18	0	1007	18	1	
656	99.93440	74	23	0	1006	16	3	
5675	99.43250	202	6	0	1013	25	21	
125	99.98750	45	1	0	1011	23	0	
1721	99.82790	168	7	0	1002	49	41	
263	99.97370	57	6	0	1006	26	2	
109	99.98910	21	3	0	1006	18	1	
7816	99.21840	107	8	0	1016	39	19	

# OS Noise tracer options

- Configuration files inside `/sys/kernel/trace/osnoise`
  - `cpus`: CPUs at which an osnoise thread will execute.
  - `period_us`: the period of the osnoise thread.
  - `runtime_us`: how long an osnoise thread will look for noise in the period
  - `stop_tracing_us`: stop system tracing if a single noise is  $\geq$  than set here
  - `Stop_tracing_total_us`: stop system tracing if total noise is  $\geq$  than set here
- `/sys/kernel/trace/tracing_threshold`
  - The minimum delta between two `time()` reads to be considered as noise, in us.
  - When set to 0, the default value will be used, which is currently 5 us.

# osnoise analysis



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# What can cause OS Noise?

- Any sort of task that interferes (preempt) the OS noise workload
- Linux task abstractions:
  - **NMI**
  - **IRQs**
  - **Softirqs**
  - **Threads**
- But also the hardware can interfere
  - **SMPs**
  - **VMs**

# osnoise tracepoints

- One tracepoint for each task abstraction:
  - osnoise:**nmi**\_noise
  - osnoise:**irq**\_noise
  - osnoise:**softirq**\_noise
  - osnoise:**thread**\_noise
- They report the amount of noise
  - The values are free from nested interference
    - e.g., a thread\_noise noise is free from any IRQ/Softirq/NMI interference that it could face
- osnoise:sample\_threshold: the total noise observed by the workload

# Using osnoise tracepoints & root cause

```
[root@f32 ~]# cd /sys/kernel/tracing/
[root@f32 tracing]# echo osnoise > current_tracer
[root@f32 tracing]# echo osnoise > set_event
[root@f32 tracing]# echo 8 > osnoise/stop_tracing_us
[root@f32 tracing]# cat trace
[...]
```

osnoise/8-960	[007]	d.h.	5789.857530:	irq_noise: local_timer:236	start 5789.857527123	duration 1867 ns
osnoise/8-961	[008]	d.h.	5789.857532:	irq_noise: local_timer:236	start 5789.857529929	duration 1845 ns
osnoise/8-961	[008]	dNh.	5789.858408:	irq_noise: local_timer:236	start 5789.858404871	duration 2848 ns
migration/8-54	[008]	d...	5789.858413:	thread_noise: migration/8:54	start 5789.858409300	duration 3068 ns
osnoise/8-961	[008]	....	5789.858413:	sample_threshold: start 5789.858404555	<b>duration 8812 ns</b>	<b>interferences 2</b>



timerlat tracer



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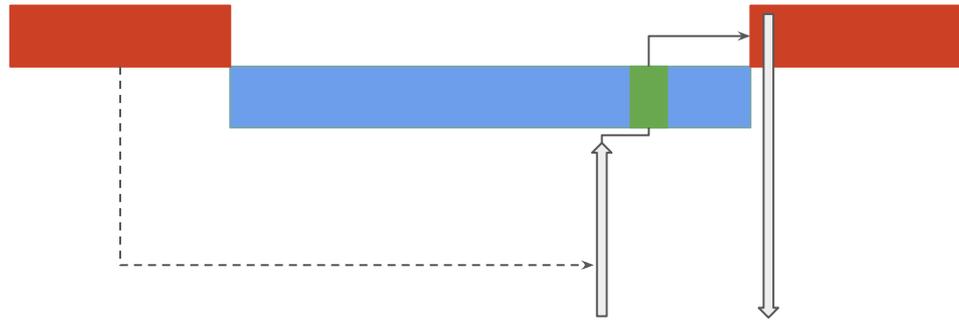
# Timer latency

- Timer latency has been used as a metric by the real-time Linux kernel developers
  - `cyclictest` is indeed a timer testing tool
- It empirically measures the observed **scheduling latency** of the highest priority thread
  - or a thread at any priority
- **timerlat tracer** measure the same metric, but it is integrated with tracing.

# Timer latency and safety critical systems

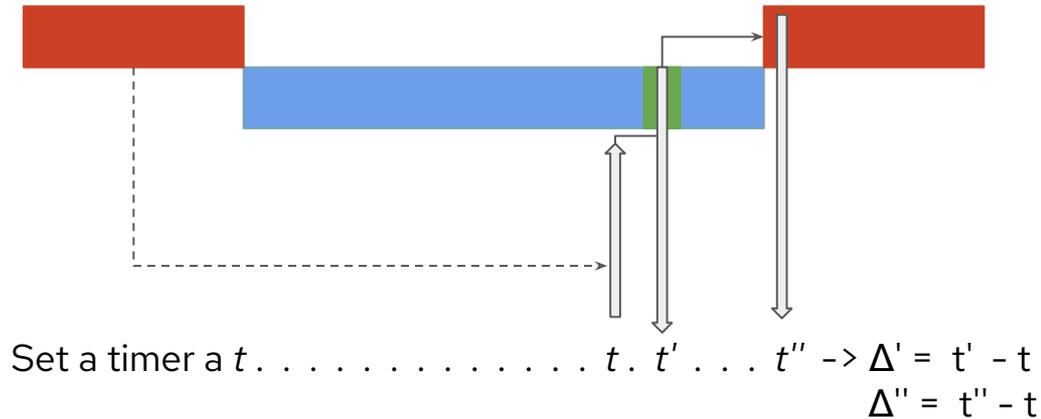
- Measuring the timer latency is equivalent to measure the response to an external event
  - For timer trigger events
  - Or any like any interrupt from hardware
- The timerlat tracer is useful:
  - To assess that externally triggered events are timely handled.
  - To identify how much activation latency non-critical load is adding to the critical load
    - Causing delay in the response time of critical workload

# Task activation delay



Set a timer at  $t$  . . . . .  $t'$  . . . . .  $\Delta = t' - t$

# Task activation delay





# Timerlat tracer options

- Configuration files inside `/sys/kernel/trace/osnoise`
  - `cpus:` CPUs at which a timerlat thread will execute.
  - `period_us:` the timer period
  - `stop_tracing_us:` stop the system tracing if IRQ latency  $\geq$  than set here
  - `stop_tracing_total_us:` stop the system tracing if thread latency is  $\geq$  than set here
  - `print_stack:` save the IRQ stack trace to print in case of latency  $\geq$  than set

# timerlat analysis



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# What can cause timer latency?

- Linux task abstractions:
  - NMI
  - IRQs
  - softirqs
  - Higher priority thread
- Previously running thread with **preemption || irq** disabled

# osnoise tracepoints

- One tracepoint for each task abstraction:
  - osnoise:**nmi**\_noise
  - osnoise:**irq**\_noise
  - osnoise:**softirq**\_noise
  - osnoise:**thread**\_noise
- They report the amount of noise
- softirq and thead noise account from the timer IRQ handler
  - **So it measures the noise actually added to timer thread**

# Using the timerlat tracer

```
[root@f32 ~]# cd /sys/kernel/tracing/
[root@f32 tracing]# echo timerlat > current_tracer
[root@f32 tracing]# echo 1 > events/osnoise/enable
[root@f32 tracing]# echo 500 > osnoise/stop_tracing_total_us
[root@f32 tracing]# echo 500 > osnoise/print_stack
[root@f32 tracing]# tail -21 per_cpu/cpu7/trace
    insmod-1026    [007] dN.h1..  200.201948: irq_noise: local_timer:236 start 200.201939376 duration 7872 ns
    insmod-1026    [007] d..h1..  200.202587: #29800 context   irq timer_latency    1616 ns
    insmod-1026    [007] dN.h2..  200.202598: irq_noise: local_timer:236 start 200.202586162 duration 11855 ns
    insmod-1026    [007] dN.h3..  200.202947: irq_noise: local_timer:236 start 200.202939174 duration 7318 ns
    insmod-1026    [007] d...3..  200.203444: thread_noise:  insmod:1026 start 200.202586933 duration 838681 ns
    timerlat/7-1001 [007] .....  200.203445: #29800 context thread timer_latency    859978 ns
    timerlat/7-1001 [007] ....1.. 200.203446: <stack trace>
=> timerlat_irq
=> __hrtimer_run_queues
=> hrtimer_interrupt
=> __sysvec_apic_timer_interrupt
[...continue...]
```

# Using the timerlat tracer

```
[...]
  insmod-1026    [007] d..h1.. 200.202587: #29800 context    irq timer_latency      1616 ns
  insmod-1026    [007] dN.h2.. 200.202598: irq_noise: local_timer:236 start 200.202586162 duration 11855 ns
  insmod-1026    [007] dN.h3.. 200.202947: irq_noise: local_timer:236 start 200.202939174 duration 7318 ns
  insmod-1026    [007] d...3.. 200.203444: thread_noise:  insmod:1026 start 200.202586933 duration 838681 ns
  timerlat/7-1001 [007] ..... 200.203445: #29800 context thread timer_latency    859978 ns
  timerlat/7-1001 [007] ....1.. 200.203446: <stack trace>
=> timerlat_irq
=> __hrtimer_run_queues
=> hrtimer_interrupt
=> __sysvec_apic_timer_interrupt
=> asm_call_irq_on_stack
=> sysvec_apic_timer_interrupt
=> asm_sysvec_apic_timer_interrupt
=> delay_tsc
=> dummy_load_1ms_pd_init
=> do_one_initcall
=> do_init_module
=> __do_sys_finit_module
=> do_syscall_64
=> entry_SYSCALL_64_after_hwframe
```



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# Real-time Linux Analysis

- **rtla** is a **user-space** tool that serves as **front-end** for **setup, tracing** and **data analysis**
- **It transforms the tracers into a benchmark tool**
- It is in **C**, hosted inside the **tools/tracing/rtla** in the **kernel repo**
- Two tools in the initial implementation:
  - **rtla osnoise**: measures the operating system noise
  - **rtla timerlat**: measures the timer latency

# rtla osnoise

- **rtla osnoise** is an interface to **osnoise tracer**
  - Adds more options to the tracer
    - e.g., setting priority to threads
  - Interface for other tracing features like tracepoints and histograms
- Two different modes:
  - **osnoise top**: shows an interactive view of the osnoise summary output
  - **osnoise hist**: shows a histogram of the osnoise sample tracepoint

# rtla timerlat

- **rtla timerlat** is an interface to **timerlat tracer**
  - Adds more options to the tracer
    - e.g., setting priority to threads
  - Interface for other tracing features like tracepoints and histograms
- Two different modes:
  - **timerlat top**: shows an interactive view of the osnoise summary output
  - **timerlat hist**: shows a histogram of the osnoise sample tracepoint

# rtla timerlat: how easy it is?

- I am a **user** testing my **kernel-rt** setup, and I want to **measure** the latency and generate a **report** if my **latency is higher than 50 us**?
- Nowadays, this requires:
  - Using **cyclictest** with stop tracing
  - **Instructions about setting tracing** (asking in IRC or mailing list?)
  - Figuring things out from tracing, computing execution time **by hand**/scripts.
- **How much easier is my life using rtla?**

# rtla timerlat: how easy it is?

- **timerlat top -a 50**

# rtla timerlat: how easy it is?

- **timerlat top -a 50**
- It measures latency
- Sets up a tracing session
- Enables the minimum required trace events
  - osnoise: events
  - stacktrace for the IRQ handler
- Stops the trace if a 50 us latency is hit, saving the result to a timerlat\_trace.txt



RTLA is the automation of an expert  
analysis



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# RTLA demo

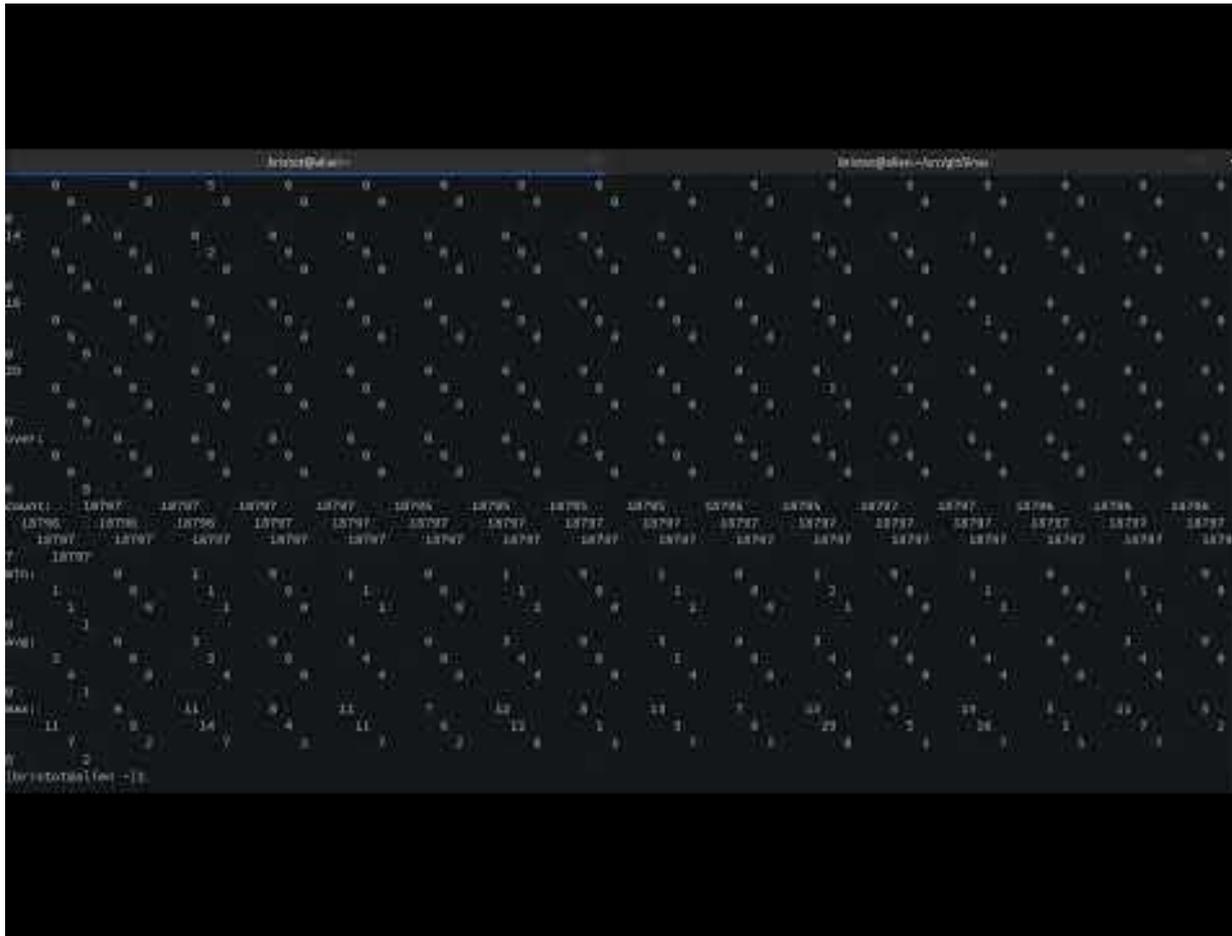


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# Demo:



The image shows a terminal window with a dark background. At the top, there are two tabs: 'root@kali:~' and 'kali@kali:~/rogo2/rogo'. The main content of the terminal is a large grid of numbers and symbols, including '0', '1', '2', '3', '4', '5', '6', '7', '8', '9', 'A', 'B', 'C', 'D', 'E', 'F', 'G', 'H', 'I', 'J', 'K', 'L', 'M', 'N', 'O', 'P', 'Q', 'R', 'S', 'T', 'U', 'V', 'W', 'X', 'Y', 'Z', and various punctuation marks. The numbers are arranged in a grid that appears to be a representation of a cryptographic key stream or a similar data structure. The terminal prompt is visible at the bottom left as '(or)root@kali:~)'. The overall appearance is that of a complex data visualization or a cryptographic demonstration.

<https://www.youtube.com/watch?v=3sGM076mLRQ&t=1s>

# RTLA status

- **RTLA is upstream!**
  - **Tracers since 5.14**
  - **RTLA since 5.17**
  - Advanced trace support queued for 5.18
- Tracers enabled on Fedora/CentOS/Red Hat
- RTLA package on the way to Fedora/CentOS/Red Hat
- More tools and analysis are on the way
  - rtsl is next -> <https://bristot.me/demystifying-the-real-time-linux-latency/>

Thanks



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